

An Improved Detection Method of STATCOM Compensating Reference Current

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Abstract—With the continuous development of power electronics technology, static synchronous compensator (STATCOM) structure increasingly multiplex. When the load current check point and the compensation injection point of STATCOM in different position and exist the difference of the phase and amplitude, which can produce a difference of detection. To solve this problem, this paper proposes an improved STATCOM compensation instruction current detection method based on i_p - i_q algorithm. This method can eliminate the error and improve the detection accuracy by setting the preset phase angle and proportional integral (PI) controller according to the difference of voltage phase and amplitude between the check point and the compensation point, thus breaking the limitation that traditional i_p - i_q algorithm is only applicable in the case of that the detecting point and the compensation point in the same position, which improve the accuracy of detection. Theoretical analysis and simulation results show the effectiveness of the proposed method in this paper.

Keywords-STATCOM; detection difference; compensation instruction current; i_p - i_q algorithm; preset phase angle

I. INTRODUCTION

In recent years, the harmonic pollution in the modern power grid is becoming increasingly serious which leading to the stable operation of power system is affected [1]. In order to improve the power quality problem more accurately and effectively, people has been proposed various compensation device. Among them, STATCOM can be real-time dynamic compensation of power grids automatically which is representative of the latest technology in today's compensation field [2,3]. STATCOM can dynamically tracking compensation quickly and accurately depending on the detection method of command current, so people proposed various detection methods. The harmonic current detection method based on the adaptive interference canceling theory has the detection ability of adaptive tracking, but the dynamic response is slow and exist a delay [4]. The harmonic current detection method based on the neural network method and the wavelet transform method has high detection precision, but it has computational complexity and workload shortcomings [5,6]. The harmonic current detection method based on the Fourier transform (FFT) has high detection precision and its simple to realize, but it also has computational complexity and real-time problem. The i_p - i_q

algorithm based on the instantaneous reactive power theory has better real-time and fast dynamic response speed, so it has been widely used in the detection of STATCOM compensation reference current [7,8]. However, the traditional i_p - i_q algorithm is only applicable in the case of that the load current detecting point and the power compensation injection point of STATCOM in same location, Therefore, there are certain restrictions on the detecting of reference current for complex structure STATCOM in the engineering practice.

This paper proposed an improved i_p - i_q algorithm to detect STATCOM compensation reference current. This method introducing the voltage phase information of detecting point and compensation point, eliminating detection error and improving the detection accuracy by setting the phase presetting angle and PI controller, thus breaking the limitation that traditional i_p - i_q algorithm is only applicable in the case of that the detecting point and compensation point in the same position.

II. TRADITIONAL i_p - i_q ALGORITHM

The instantaneous reactive power theory is based on the theorem of instantaneous active power p and instantaneous imaginary power q . With the continuous development and improvement, it proposed the p - q and i_p - i_q algorithm based on the instantaneous reactive power theory. Among them, The i_p - i_q algorithm has smaller error and wider application in the detection of STATCOM compensation reference current [9], and the schematic diagram shown in Fig. 1.

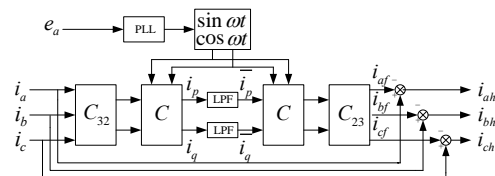


Figure 1. The schematic diagram of i_p - i_q detection method

Hypothesis three phase is symmetric, the detected current is as follows [10]:

$$\begin{aligned} i_a &= \sqrt{2} \sum_{n=1}^{\infty} I_n \sin(n\omega t + \varphi_n) \\ i_b &= \sqrt{2} \sum_{n=1}^{\infty} I_n \left[n \left(\omega t - \frac{2\pi}{3} \right) + \varphi_n \right] \\ i_c &= \sqrt{2} \sum_{n=1}^{\infty} I_n \left[n \left(\omega t + \frac{2\pi}{3} \right) + \varphi_n \right] \end{aligned} \quad (1)$$

Where ω is angular frequency, I_n and φ_n are valid values and initial phase angle for each current.

The detected three phase signal go through the Clark transform C_{32} and the Park transform C to get the instantaneous active current i_p and instantaneous reactive current i_q respectively as follows

$$\begin{bmatrix} i_p \\ i_q \end{bmatrix} = C \cdot C_{32} \cdot \begin{bmatrix} i_a \\ i_b \\ i_c \end{bmatrix} = \sqrt{3} \begin{bmatrix} \sum_{n=1}^{\infty} I_n \cos[(1-n)\omega t - m\varphi_n] \\ \sum_{n=1}^{\infty} \pm I_n \sin[(1-n)\omega t - \varphi_n] \end{bmatrix} \quad (2)$$

where $C = \begin{bmatrix} \sin \omega t & -\cos \omega t \\ -\cos \omega t & -\sin \omega t \end{bmatrix}$, $C_{32} = \sqrt{\frac{2}{3}} \begin{bmatrix} 1 & -\frac{1}{2} & -\frac{1}{2} \\ 0 & \frac{\sqrt{3}}{2} & -\frac{\sqrt{3}}{2} \end{bmatrix}$

After through the low pass filter (LPF), i_p , i_q turn into \bar{i}_p , \bar{i}_q . The fundamental current can be obtained through the inverse transform as follows

$$\begin{bmatrix} i_{af} \\ i_{bf} \\ i_{cf} \end{bmatrix} = C_{23} \cdot C \cdot \begin{bmatrix} \bar{i}_p \\ \bar{i}_q \end{bmatrix} = \begin{bmatrix} \sqrt{2} I_1 \sin(\omega t + \varphi_1) \\ \sqrt{2} I_1 \sin\left(\omega t - \frac{2\pi}{3} + \varphi_1\right) \\ \sqrt{2} I_1 \sin\left(\omega t + \frac{2\pi}{3} + \varphi_1\right) \end{bmatrix} \quad (3)$$

where $C_{23} = C_{32}^T$, i_{af} , i_{bf} , i_{cf} is the fundamental current of i_a , i_b , i_c respectively.

Three phase current signal minus the fundamental current signal can get harmonic current, disconnect the i_q gallery can get the sum of harmonic current and fundamental reactive current, reactive current can be obtained by inverse transformation. The resulting current signal obtained as compensating reference current of STATCOM, it can realize the compensation of load.

However, the traditional ip-iq algorithm only with the load voltage detecting point as the signal generator, requiring load detecting points and compensation injection point in the same voltage level, so it has certain restrictions of STATCOM compensation position in the engineering practice.

III. Improvement of STATCOM compensating reference current detection method

With multiplex structure of STATCOM, when the load current detection point and STATCOM compensation injection point located on different voltage levels, the voltage phase and amplitude between the detection point

and the compensation point will have a certain deviation. However, the traditional ip-iq algorithm is only applicable to the situation that detection point and compensation points at the same voltage level and the amount of information has larger deviations, which can not be directly used for compensation. This paper analysis the principle of the instantaneous reactive power theory and presents an improved detection method. The method is based on the traditional ip-iq algorithm, by introducing the voltage information e_a , e_b from the detection point and compensation point, there are two aspects have been improved: The one aspect is to eliminate the detection error caused by the phase difference by setting the preset phase angle, the other is to eliminate the detection error caused by amplitude differences by setting PID controller. The principle is shown in Fig. 2.

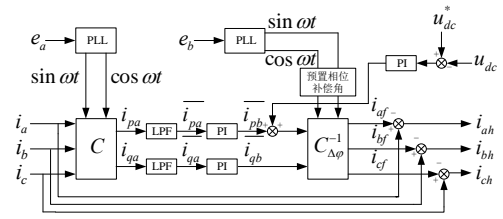


Figure 2. The principle diagram of the improved detection methods

(1) According to the difference between the load detection point voltage e_a and compensation injection point voltage e_b , setting a preset phase angle in the detection circuit, so as to eliminate the error caused by the phase difference detection. While the compensation point voltage e_b and detection point voltage e_a at different phase, it can't directly to occurs the phase of e_a as a inversion transform signal. Here set the initial phase angle of detection point voltage is 0, the difference of voltage initial phase angle between the detection and compensation point is $\Delta\varphi$, the transformation matrix C is as follow

$$C = \sqrt{\frac{2}{3}} \begin{bmatrix} \sin(\omega t) & \sin\left(\omega t - \frac{2\pi}{3}\right) & \sin\left(\omega t + \frac{2\pi}{3}\right) \\ -\cos(\omega t) & -\cos\left(\omega t - \frac{2\pi}{3}\right) & -\cos\left(\omega t + \frac{2\pi}{3}\right) \end{bmatrix} \quad (4)$$

The phase of e_b occurs as a signal of inverse transformation and introducing a preset phase angle $\Delta\varphi$ before the inverse transformation matrix $C_{\Delta\varphi}^{-1}$. The inverse transformation matrix $C_{\Delta\varphi}^{-1}$ is obtained as follow

$$C_{\Delta\varphi}^{-1} = \sqrt{\frac{2}{3}} \begin{bmatrix} \sin(\omega t + \Delta\varphi) & -\cos(\omega t + \Delta\varphi) \\ \sin\left(\omega t + \Delta\varphi - \frac{2\pi}{3}\right) & -\cos\left(\omega t + \Delta\varphi - \frac{2\pi}{3}\right) \\ \sin\left(\omega t + \Delta\varphi + \frac{2\pi}{3}\right) & -\cos\left(\omega t + \Delta\varphi + \frac{2\pi}{3}\right) \end{bmatrix} \quad (5)$$

After the improvement, the fundamental component of the DC component through the inverse transform matrix obtained from the $C_{\Delta\varphi}^{-1}$ without error, so as to improve the accuracy of detection.

(2) Increase the PI controller after the low pass filter

(LPF), use the voltage amplitude ratio between the e_a and the e_b as the adjustment coefficient of ratio control P to reduce the steady-state error. The PI controller can eliminate the static error of variables, its dynamic performance and steady state performance of anti-jamming is good. When the traditional ip-iq algorithm in detecting current, the current after through the transformation matrix C can be calculated as followed

$$\begin{bmatrix} \bar{i}_{pa} \\ \bar{i}_{qa} \end{bmatrix} = C \begin{bmatrix} \bar{i}_a \\ \bar{i}_b \\ \bar{i}_c \end{bmatrix} \quad (6)$$

Then through a low-pass filter to get the fundamental current signal \bar{i}_{pa} 、 \bar{i}_{qa} . The measurement point and the compensation point has voltage amplitude difference, in order to ensure the power balance, inversion of fundamental current can not be replaced directly. The power balance equation is as follow

$$\frac{3}{2}U_{am}I_{am} = \frac{3}{2}U_{bm}I_{bm} \quad (7)$$

Where U_{am} 、 U_{bm} is the voltage amplitude of the measurement point and the compensation point respectively, I_{am} 、 I_{bm} is the Current amplitude of the measurement point and the compensation point respectively.

Setting the amplitude ratio K_{up} between the measuring point voltage e_a and the compensation point voltage e_b as follow

$$K_{up} = \frac{U_{bm}}{U_{am}} \quad (8)$$

According to formula (7)、(8), can obtain the relationship as follow

$$I_{bm} = \frac{1}{K_{up}} I_{am} \quad (9)$$

where $1/K_{up}$ is proportional control factor. The DC component \bar{i}_{pa} 、 \bar{i}_{qa} to the PI regulator by proportional resonance operation can obtained \bar{i}_{pb} 、 \bar{i}_{qb} respectively, And then sent to an inverse transform part, can get the fundamental current as

$$\begin{bmatrix} \bar{i}_{af} \\ \bar{i}_{bf} \\ \bar{i}_{cf} \end{bmatrix} = C_{\Delta\varphi}^{-1} \begin{bmatrix} \bar{i}_{pb} \\ \bar{i}_{qb} \end{bmatrix} \quad (10)$$

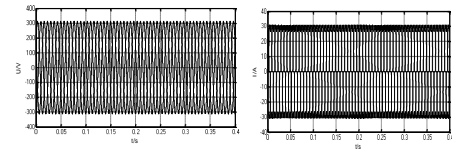
In order to make STATCOM work normally, here introduce a voltage balancing controller. to ensure u_{dc} constant. The difference value between the u_{dc} and reference voltage u_{dc}^* through a PI controller, then the value and \bar{i}_{pb} superposition to maintain effect of the voltage stability.

IV. SIMULATION AND EXPERIMENTAL RESULTS

In this paper, the STATCOM simulation model has built by using the Matlab/simulink, which verified the correctness and effectiveness of the improved detection method. The simulation model consists of the main circuit

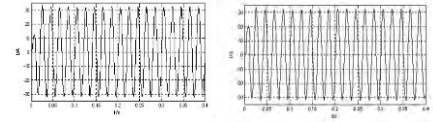
of STATCOM, signal detection circuit, control circuit and drive circuit. The simulation parameters are as follows: the power line voltage is 311V, power line current is 32A, power grid frequency is 50Hz, the load resistance is 100 Ω , the load inductance is 2mH, the circuit resistance was 5 Ω , line inductance is 2mH.

Fig .3 (a)、(b) is the waveform of power supply voltage and load current respectively, it can be clearly seen that voltage magnitude of load imbalance and serious distortion of current waveform. Fig .4 (a)、(b) is the a phase instruction current waveform of traditional ip-iq algorithm and the method proposed in this paper respectively. Through the contrast can be seen obviously, current waveform of traditional ip-iq algorithm is poor. The improved detection method proposed in this paper has good real-time and proves that the improved method can realize the accurate detection of compensation current.



(a) power supply voltage (b) load current

Figure 3. The waveform of power supply voltage and load current



(a) The traditional method (b) The improved method

Figure 4. Reference current of a phase

The method proposed in this paper apply to the experiment in the STATCOM system, the results are shown in Fig .5、6. Fig .5 is the grid current waveform before compensation, the distortion is serious. Fig .6 (a)、(b) is the grid current waveform after compensation. Starting from 0.04s to compensate the power grid, it can be seen clearly that the effect of grid current waveform compensating by traditional algorithm is poor and contains a lot of harmonic. The grid current waveform after compensation obtained by the method proposed in this paper has been quite close to the sine wave, the harmonic content is reduced from the original 4.3% to 1.2%, which verifies the feasibility and effectiveness of the proposed method.

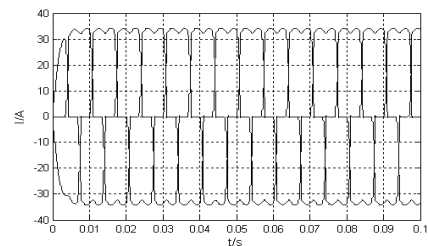
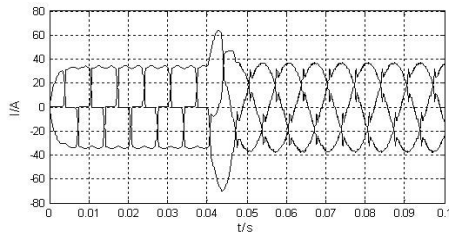
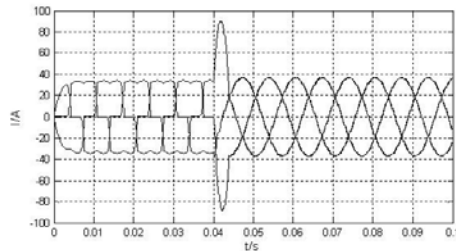


Figure 5. The grid current waveform before compensation



(a)The traditional method



(b) The improved method

Figure 6. The grid current waveform after compensation

V. Conclusions

This paper is based on the instantaneous reactive power theory and in-depth analysis of the basic principle of the i_p - i_q algorithm, it points out that the limitations of this method in the detection of STATCOM instruction current and proposes an improved instruction current detection method, which sets a phase compensation angle and add the PI controller after the low pass filter to solve the instruction current detection problem in the case of the STATCOM detection point and the compensation point in different position. Simulation experiment is carried out through the analysis of the traditional i_p - i_q algorithm and the improved method, the results shows that the improved method can detect compensation instruction current better and has more extensive scope of application.

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